03 Arduino

UART, GPS



8 Default messages

| Interface | Settings |
|------------------------|--|
| UART Output | 9600 Baud, 8 bits, no parity bit, 1 stop bit Configured to transmit both NMEA and UBX protocols, but only the following NMEA (and no UBX) messages have been activated at start-up: GGA, GLL, GSA, GSV, RMC, VTG, TXT |
| UART Input | 9600 Baud, 8 bits, no parity bit, 1 stop bit, Autobauding disabled Automatically accepts following protocols without need of explicit configuration: UBX, NMEA The GNSS receiver supports interleaved UBX and NMEA messages. |
| DDC | Fully compatible with the I ² C industry standard, available for communication with an external host CPU or u-blox cellular modules; operated in slave mode only. NMEA and UBX are enabled as input messages, only NMEA as output messages Maximum bit rate 400 kb/s. |
| TIMEPULSE (1Hz Nav) | 1 pulse per second, synchronized at rising edge, pulse length 100 ms |

Table 9: Default messages



Please refer to the *u-blox 7 Receiver Description Including Protocol Specification* [2] for information about further settings.

uBlox

Standard precision GNSS and dead reckoning modules

| Model | | Cate | gory | | GNSS | | | | | | Inter | faces | | Features | | | | | | | | | | Grade | | | |
|---------|-------------------------|---------------------|----------------|--------|------------|---------|---------|--------|------------------------------|------|-------|-------|--------------------|----------------------|--------------|----------------|----------------|-------------|------------|------------------|-----------------|---|-----------|----------|--------------|------------|--|
| | Standard Precision GNSS | High Precision GNSS | Dead Reckoning | Timing | GPS / QZSS | GLONASS | Galileo | BeiDou | Number of Concurrent GNSS | UART | usa | SPI | DDC (PC compliant) | Programmable (Flash) | Data logging | Additional SAW | Additional LNA | RTC crystal | Oscillator | Built-in antenna | Built-in sensor | Built-in antenna supply and supervisor | Timepulse | Standard | Professional | Automotive | |
| EVA-M8M | • | | | | • | • | Е | • | 3 | • | • | • | • | ۰ | 0 | | | 0 | С | | | | 1 | | | | |
| EVA-7M | • | | | | • | • | | | 1 | • | • | • | • | | | | | 0 | С | | | | 1 | | | | |
| LEA-M8S | • | | | | • | • | | • | 2 | • | • | | • | | | • | | • | Т | | | • | 1 | | | | |
| MAX-M8C | • | | | | • | • | | • | 2 | • | | | • | | | | | * | C | | | | 1 | | | | |
| MAX-M8Q | • | | | | • | • | | • | 2 | • | | | • | | | | | • | Т | | | | 1 | | | | |
| MAX-M8W | • | | | | • | • | | • | 2 | • | | | • | | | | | • | Т | | | • | 1 | | | | |
| MAX-7C | • | | | | • | • | | | 1 | • | | | • | | | | | + | C | | | | 1 | | | | |
| MAX-7Q | • | | | | • | • | | | 1 | • | | | • | | | | | • | Т | | | | 1 | | | | |
| MAX-7W | • | | | | ٠ | • | | | 1 | • | | | • | | | | | ٠ | Т | | | • | 1 | | | | |
| NEO-M8N | • | | | | • | ٠ | • | • | 3 | ٠ | ٠ | • | • | • | ٠ | ٠ | • | • | Т | | | | 1 | | | | |
| NEO-M8Q | | | | | • | • | | • | 2 | • | • | • | • | | | • | • | • | Т | | | | 1 | | | | |
| NEO-M8M | · | | | | ٠ | • | | • | 2 | · | • | • | • | | | | | • | С | | | | 1 | | | | |
| NEO-7N | • | | | | • | • | | | 1 | • | • | • | • | ٠ | ٠ | • | • | • | Т | | | | 1 | | | | |
| NEO-7M | · | | | | ٠ | • | | | 1 | · | • | • | ٠ | | | | | • | C | | | | 1 | | | | |
| CAM-M8Q | • | | | | • | • | | • | 2 | • | | • | • | | | • | • | • | Т | • | | | 1 | | | | |
| CAM-M8C | · | | | | ٠ | • | | • | 2 | · | | • | • | | | • | • | * | С | • | | | 1 | | | | |
| PAM-7Q | ٠ | | | | • | | | | 1 | ٠ | | | • | | | | | • | Т | • | | | 1 | | | | |
| NEO-M8L | | | ADR | | • | • | • | • | 3 | ٠ | • | • | • | • | ٠ | | | • | C | | ٠ | | 1 | | | | |
| NEO-M8U | | | UDR | | • | • | • | • | 3 | • | • | • | • | • | • | | | • | C | | • | | 1 | | | | |

GPS <-> Arduino Serial3

9600 8/n/1

Arduino SerialO <-> PC

115200 8/n/1

```
void setup() {
      Serial.begin (115200);
      Serial3.begin (9600);
void loop() {
      while (Serial3.available()) {
      Serial.println(Serial3.readStringUntil('\n'));
      while (Serial.available()) {
      Serial3.println(Serial.readString());
```

```
Text Console
          $GPGSA.A.3.09.23.16.30,05,02,07,06,,,,2.22,1.11,1.92*01.
09:28:45
09:28:45
          $GPGSV,3,1,11,02,32,276,25,03,02,137,28,05,21,309,36,06,27,224,09*75.
          $GPGSV.3.2.11.07.70.184.31.09.67.066.46.16.21.047.44.23.34.082.46*74.
09:28:45
09:28:45
          $GPGSV,3,3,11,26,04,025,42,29,00,334,,30,40,207,23*44.
          $GPGLL.4732.05981.N.01902.03999.E.092845.00.A.A*6C.
09:28:45
09:28:46
          $GPRMC.092846.00.A.4732.05991.N.01902.04002.E.0.105..080316...A*73.
09:28:46
          $GPVTG..T..M.0.105.N.0.194.K.A*2B.
          $GPGGA,092846.00,4732.05991,N,01902.04002,E,1,08,1.11,158.2,M,39.4,M,,*5E.
09:28:46
          $GPGSA.A.3.09.23,16,30,05,02,07,06,,,,,2.22,1.11,1.92*01.
09:28:46
09:28:46
          $GPGSV,3,1,11,02,32,276,26,03,02,137,27,05,21,309,36,06,27,224,09*79.
09:28:46
          $GPGSV.3.2.11.07.70.184.31.09.67.066.46.16.21.047.44.23.34.082.46*74.
09:28:46
          $GPGSV,3,3,11,26,04,025,42,29,00,334,,30,40,207,23*44.
09:28:46
          $GPGLL,4732.05991,N,01902.04002,E,092846.00,A,A*62.
          $GPRMC,092847.00,A,4732.05995,N,01902.04003,E,0.048..080316...A*7F.
09:28:47
09:28:47
          $GPVTG..T..M.O.048.N.O.089.K.A*2E.
          $GPGGA,092847.00,4732.05995,N,01902.04003,E,1,07.1.32.158.0.M,39.4.M..*56.
09:28:47
09:28:47
          $GPG5A,A,3,09,23,16,30,05,02,07,,,,,2.60,1.32,2.24*0E.
09:28:47
          $GPGSV,3,1,11,02,32,276,26,03,02,137,27,05,21,309,36,06,27,224,09*79.
09:28:47
          $GPGSV,3,2,11,07,70,184,30,09,67,066,46,16,21,047,44,23,34,082,46*75.
09:28:47
          $GPGSV.3.3.11.26.04.025.42.29.00.334..30.40.207.23*44.
09:28:47
          $GPGLL.4732.05995.N.01902.04003.E.092847.00.A.A*66.
          $GPRMC,092848.00,A,4732.05997,N,01902.04003,E,0.107,,080316,,,A*78.
09:28:48
09:28:48
          $GPVTG.,T.,M.0.107,N.0.198,K.A*25.
09:28:48
          $GPGGA.092848.00.4732.05997.N.01902.04003.E.1.07.1.32.157.9.M.39.4.M..*5D.
09:28:48
          $GPGSA,A,3,09,23,16,30,05,02,07,...,2.60,1.32,2.24*0E.
09:28:48
          $GPGSV,3,1,11,02,32,276,26,03,02,137,28,05,21,309,37,06,27,224,09*77.
09:28:48
          $GPGSV,3,2,11,07,70,184,31,09,67,066,46,16,21,047,45,23,34,082,46*75.
09:28:48
          $GPGSV,3,3,11,26,04,025,42,29,00,334,,30,40,207,23*44.
09:28:48
          $GPGLL,4732.05997,N,01902.04003,E,092848.00,A,A*6B.
          $GPRMC,092849.00,A,4732.05994,N,01902.03999,E,0.119.,080316...A*78.
09:28:49
09:28:49
          $GPVTG..T..M.O.119.N.O.221.K.A*2B.
09:28:49
          $GPGGA,092849.00,4732.05994,N,01902.03999,E,1,07,1.32,157.6,M,39.4.M..*5D.
09:28:49
          $GPGSA,A,3,09,23,16,30,05,02,07,...,2.60,1.32,2.24*0E.
09:28:49
          $GPGSV.3.1.11.02.32.276.26.03.02.137.28.05.21.309.37.06.27.224.09*77.
          $GPGSV,3,2,11,07,70,184,30,09,67,066,46,16,21,047,45,23,34,082,46*74.
09:28:49
09:28:49
          $GPGSV,3,3,11,26,04,025,42,29,00,334,,30,40,207,22*45.
09:28:49
          $GPGLL,4732.05994,N,01902.03999,E,092849.00,A,A*64.
09:28:50
          $GPRMC,092850.00,A,4732.05988,N,01902.03994,E,0.031,,080316,,,A*7B.
09:28:50
          $GPVTG.,T.,M.0.031,N.0.057,K.A*23.
09:28:50
          $GPGGA, 092850.00, 4732.05988, N, 01902.03994, E, 1, 07, 1, 32, 157, 4, M, 39, 4, M, . *57.
09:28:50
          $GPGSA.A.3.09.23.16.30.05.02.07.....2.60.1.32.2.24*0E.
09:28:50
          $GPGSV,3,1,11,02,32,276,26,03,02,137,27,05,21,309,37,06,27,224,09*78.
09:28:50
          $GPGSV,3,2,11,07,70,184,30,09,67,066,46,16,21,047,45,23,34,082,46*74.
09:28:50
          $GPGSV.3.3.11.26.04.025.42.29.00.334..30.40.207.22*45.
          $GPGLL.4732.05988.N.01902.03994.E.092850.00.A.A*6C.
09:28:50
```

NMEA 0183

http://aprs.gids.nl/nmea/

• \$GPRMC

Recommended minimum specific GPS/Transit data

\$GPGGA

Global Positioning System Fix Data

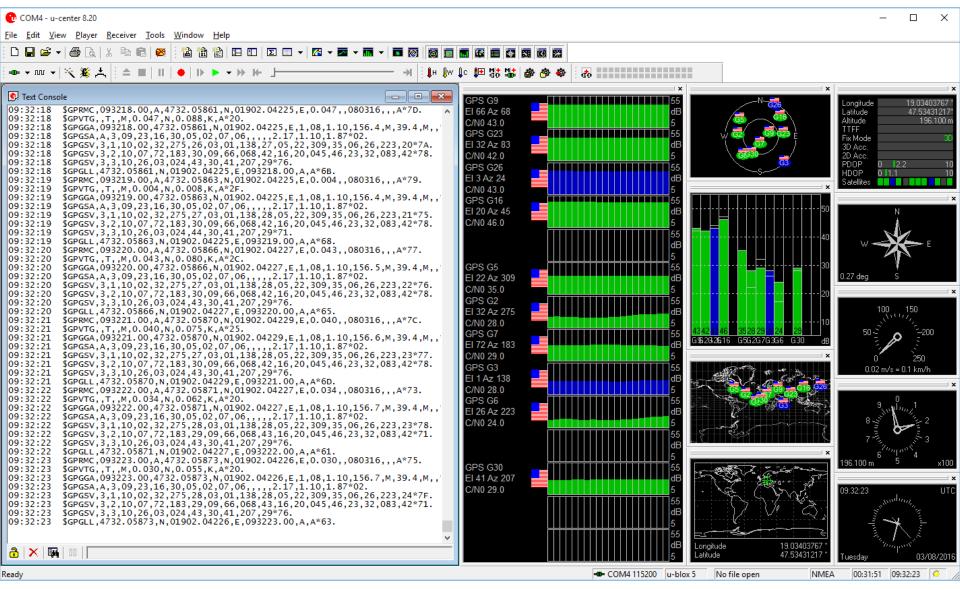
\$GPGLL

Geographic Position, Latitude / Longitude and time

\$GPGSA

GPS DOP and active satellites

uBlox uCenter



```
char delimiters[] = "$,*";

char *GPSdata = "$GPRMC,080.......3,E,A*1B\n\

$GPRMB,A,,,,,,,,,,,,V,A*1C\n\

$GPGGA,080232,47.......7,M,41.0,M,,*70\n\

...

$GPGSA,A,2,11,,,18,19,,22,,,,4.0,3.9,1.0*3D\n\,
```

strtok_r is my friend ©